



D: r, l, m, I_s
 U: VPR (LR II druhu)

$$\frac{d}{dt} \left(\frac{\partial E_k}{\partial \dot{q}_i} \right) - \frac{\partial E_k}{\partial q_i} = Q_i$$

$$E_k = \frac{1}{2} m \dot{x}_s^2 + \frac{1}{2} m \dot{y}_s^2 + \frac{1}{2} I_s \dot{\varphi}^2$$

$$q_r = \varphi \text{ (1st. volnosti)}$$

$$x_s = r \sin \varphi - r \varphi \cos \varphi$$

$$y_s = r \cos \varphi + r \varphi \sin \varphi$$

$$\dot{x}_s = r \cos \varphi \dot{\varphi} - r \dot{\varphi} \cos \varphi + r \varphi \sin \varphi \dot{\varphi}$$

$$\dot{y}_s = -r \sin \varphi \dot{\varphi} + r \dot{\varphi} \sin \varphi + r \varphi \cos \varphi \dot{\varphi}$$

$$\delta y_s = r \varphi \cos \varphi d\varphi$$

$$\dot{x}_s^2 + \dot{y}_s^2 = r^2 \dot{\varphi}^2 \sin^2 \varphi + r^2 \dot{\varphi}^2 \cos^2 \varphi = (r \dot{\varphi})^2$$

$$E_k = \frac{1}{2} m (r \dot{\varphi})^2 + \frac{1}{2} I_s \dot{\varphi}^2 = \frac{1}{2} [m (r \dot{\varphi})^2 + I_s \dot{\varphi}^2]$$

$$\frac{\partial E_k}{\partial \dot{\varphi}} = \frac{1}{2} [m (r \dot{\varphi})^2 + I_s \dot{\varphi}^2] \cdot 2 \dot{\varphi}$$

$$\frac{d}{dt} \left(\frac{\partial E_k}{\partial \dot{\varphi}} \right) = [m r^2 2 \dot{\varphi}] \ddot{\varphi} + [m (r \dot{\varphi})^2 + I_s \dot{\varphi}^2] \dot{\varphi}$$

$$= [m (r \dot{\varphi})^2 + I_s \dot{\varphi}^2] \ddot{\varphi} + 2 m r^2 \dot{\varphi} \dot{\varphi}^2$$

$$\frac{\partial E_k}{\partial \varphi} = \frac{1}{2} [m r^2 2 \varphi] \dot{\varphi}^2 = m r^2 \varphi \dot{\varphi}^2$$

$$Q dq = Q d\varphi = -G dy_s \Rightarrow Q d\varphi = -G r \varphi \cos \varphi d\varphi$$

$$\boxed{[m (r \dot{\varphi})^2 + I_s \dot{\varphi}^2] \ddot{\varphi} + 2 m r^2 \dot{\varphi} \dot{\varphi}^2 - m r^2 \varphi \dot{\varphi}^2 = -G r \varphi \cos \varphi} \text{ VPR}$$