



$$\frac{d}{dt} \left(\frac{\partial E_k}{\partial \dot{q}_r} \right) - \frac{\partial E_k}{\partial q_r} = Q$$

↑ volnosti $\rightarrow q_r = \varphi$

$$x_{s_2} = e \cos \varphi$$

$$y_{s_2} = e \sin \varphi$$

$$\dot{x}_{s_2} = -e \sin \varphi \dot{\varphi}$$

$$\dot{y}_{s_2} = e \cos \varphi \dot{\varphi}$$

$$\dot{x}_{s_2}^2 + \dot{y}_{s_2}^2 = e^2 \dot{\varphi}^2$$

$$y_{s_3} = e \sin \varphi + r + \text{konst.}$$

$$\dot{y}_{s_3} = e \cos \varphi \dot{\varphi}$$

$$E_k = \frac{1}{2} m_2 (\dot{x}_{s_2}^2 + \dot{y}_{s_2}^2) + \frac{1}{2} I_{2s_2} \dot{\varphi}^2 + \frac{1}{2} m_3 \dot{y}_{s_3}^2 \quad I_{20}$$

$$E_k = \frac{1}{2} m_2 e^2 \dot{\varphi}^2 + \frac{1}{2} I_{2s_2} \dot{\varphi}^2 + \frac{1}{2} m_3 e^2 \cos^2 \varphi \dot{\varphi}^2 = \frac{1}{2} (I_{2s_2} + m_2 e^2) \dot{\varphi}^2 + \frac{1}{2} m_3 e^2 \cos^2 \varphi \dot{\varphi}^2$$

$$E_k = \frac{1}{2} (I_{20} + m_3 e^2 \cos^2 \varphi) \dot{\varphi}^2$$

$$\frac{\partial E_k}{\partial \dot{\varphi}} = \frac{1}{2} (I_{20} + m_3 e^2 \cos^2 \varphi) 2 \dot{\varphi}, \quad \frac{d}{dt} \left(\frac{\partial E_k}{\partial \dot{\varphi}} \right) = (I_{20} + m_3 e^2 \cos^2 \varphi) \ddot{\varphi} + m_3 e^2 2 \cos \varphi (-\sin \varphi) \dot{\varphi} \dot{\varphi}$$

$$\frac{\partial E_k}{\partial \varphi} = \frac{1}{2} (m_3 e^2 2 \cos \varphi (-\sin \varphi)) \dot{\varphi}^2$$

$$Q \delta q_r = M_2 \delta \varphi - G_2 \delta y_{s_2} - G_3 \delta y_{s_3} - F_3 \cos \beta \delta y_{s_3} - F_p \delta y_{s_3}, \quad F_p = k(e \sin \varphi + r)$$

$$Q \delta \varphi = M_2 \delta \varphi - G_2 e \cos \varphi \delta \varphi - [G_3 + F_3 \cos \beta + k(e \sin \varphi + r)] e \cos \varphi \delta \varphi$$

$$(I_{20} + m_3 e^2 \cos^2 \varphi) \ddot{\varphi} - 2 m_3 e^2 \sin \varphi \cos \varphi \dot{\varphi}^2 + m_3 e^2 \sin \varphi \cos \varphi \dot{\varphi}^2 =$$

$$= M_2 - [G_2 + G_3 + F_3 \cos \beta + k(e \sin \varphi + r)] e \cos \varphi$$

VPR