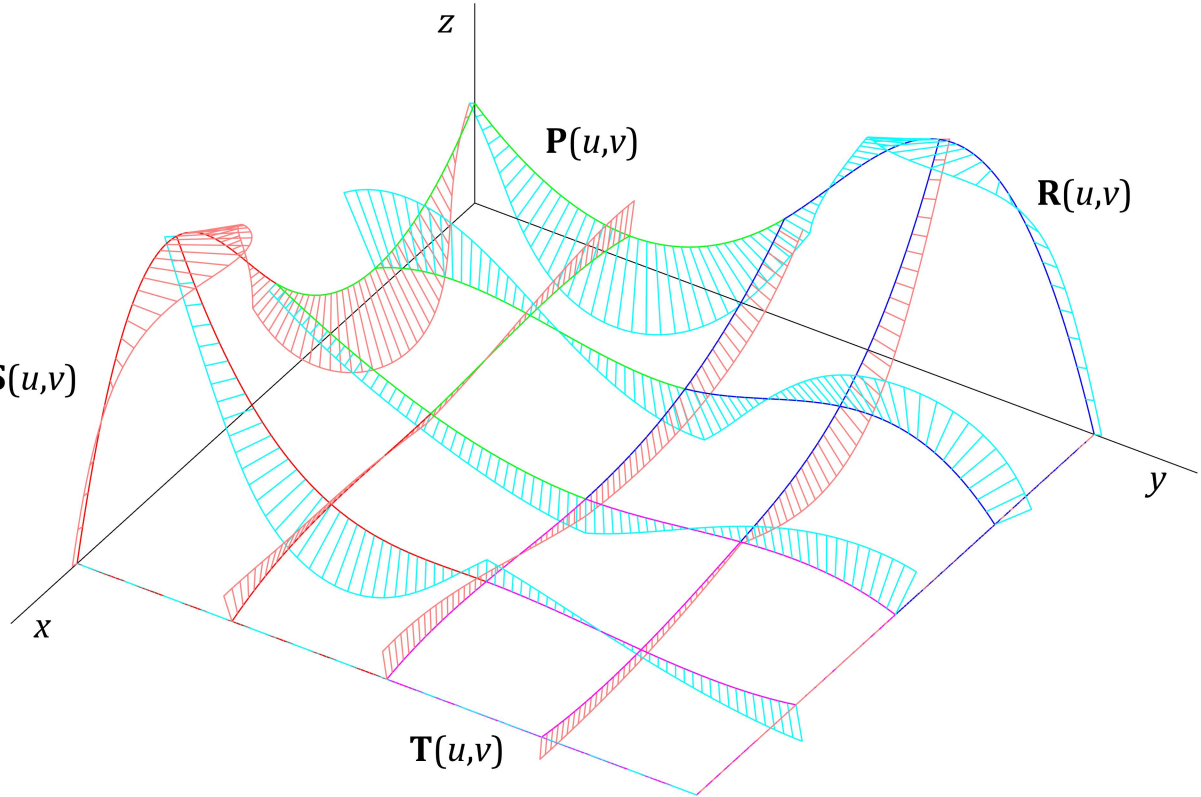
z
P(u,v)
R(u,v)
S(u,v)
y
x
T(u,v)