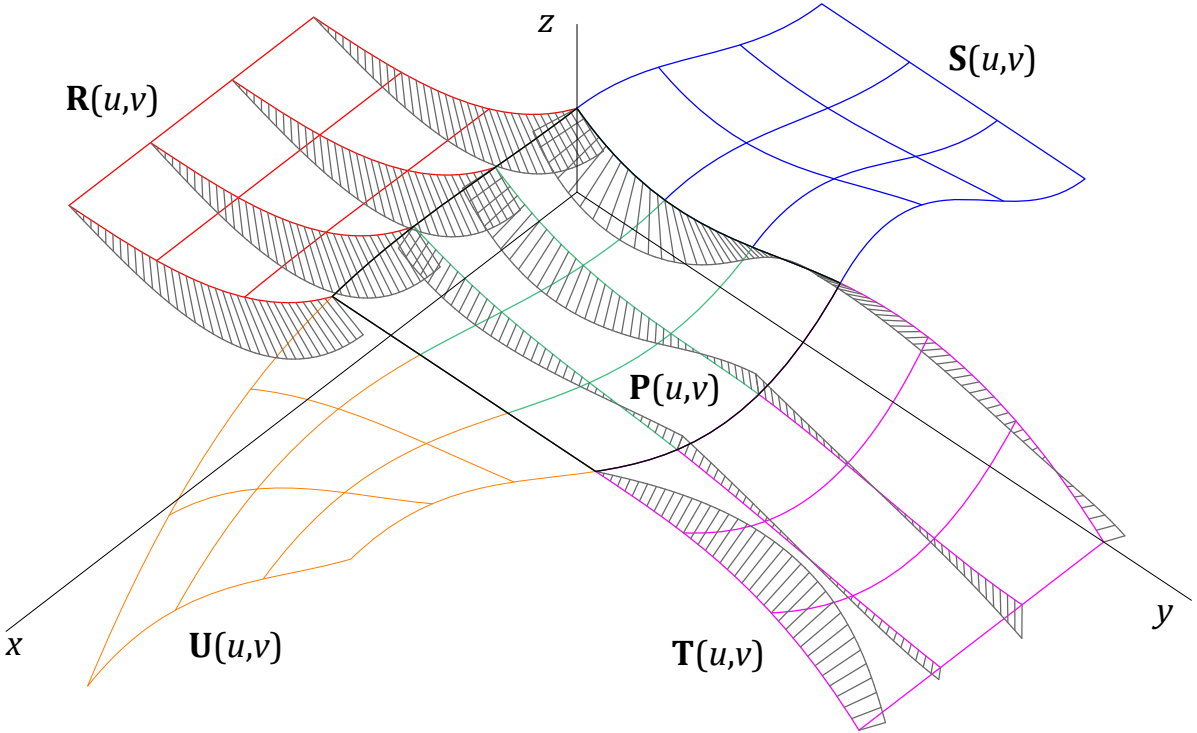
z
S(u,v)
R(u,v)
P(u,v)
x
U(u,v)
T(u,v)
y