

Computer graphics

Lesson 4

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Coons cubic curve

- approximate curve, given points P_0 , P_1 , P_2 and P_3
- vector equation:

$$\mathbf{P}(t) = C_0(t)\mathbf{P}_0 + C_1(t)\mathbf{P}_1 + C_2(t)\mathbf{P}_2 + C_3(t)\mathbf{P}_3, \quad t \in [0, 1]$$

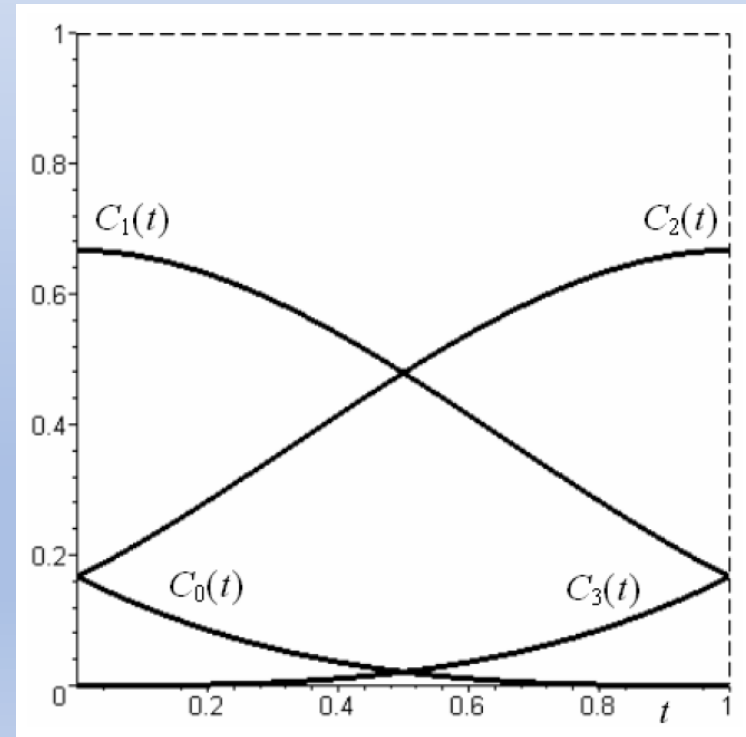
basis functions are Coons polynomials:

$$C_0(t) = \frac{1}{6}(1-t)^3,$$

$$C_1(t) = \frac{1}{6}(3t^3 - 6t^2 + 4),$$

$$C_2(t) = \frac{1}{6}(-3t^3 + 3t^2 + 3t + 1),$$

$$C_3(t) = \frac{1}{6}t^3,$$



Coons cubic curve

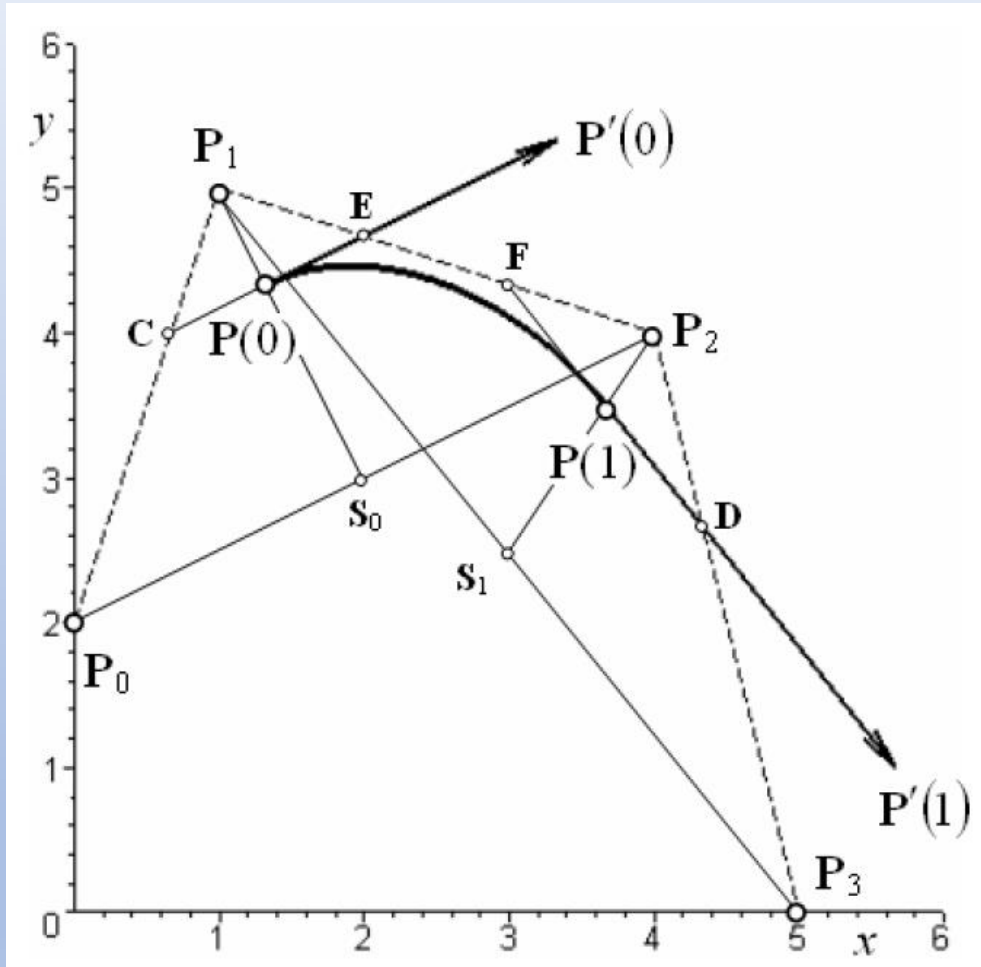
- **properties:**

1. values of Coons polynomials are <1 for any value of parameter $t \rightarrow$ curve does not pass through any given control point
2. point $P(0)$ lies at the „*ant centroid*“ of triangle $P_0P_1P_2$ constructed with respect to control point P_1
3. point $P(1)$ lies at the „*ant centroid*“ of triangle $P_1P_2P_3$ constructed with respect to control point P_2
4. tangent vectors in $P(0)$ and $P(1)$ are given by equations:

$$\mathbf{P}'(0) = \frac{1}{2} \overrightarrow{\mathbf{P}_0\mathbf{P}_2} = \frac{1}{2}(\mathbf{P}_2 - \mathbf{P}_0)$$

$$\mathbf{P}'(1) = \frac{1}{2} \overrightarrow{\mathbf{P}_1\mathbf{P}_3} = \frac{1}{2}(\mathbf{P}_3 - \mathbf{P}_1)$$

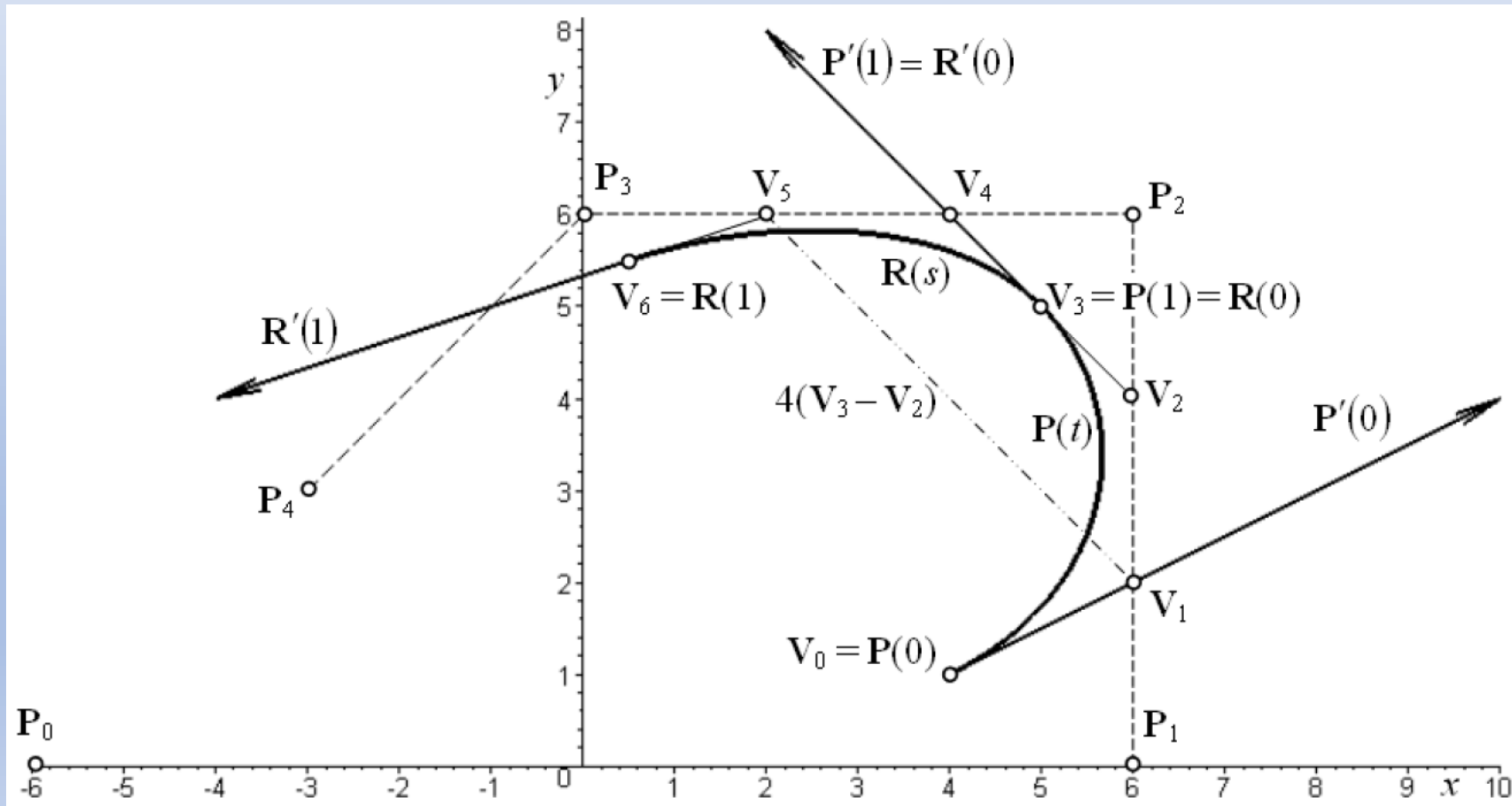
Coons cubic curve



5. tangent line at the initial point intersects legs P_0P_1 and P_1P_2 at one third from control point P_1 (points C , E) and leg P_1P_2 intersects the tangent vector $P'(0)$ at one third from point $P(0)$ (point E)
6. tangent line at the terminal point intersects legs P_1P_2 and P_2P_3 at one third from control point P_2 (points F , D) and leg P_2P_3 intersects the tangent vector $P'(1)$ at one third from point $P(1)$ (point D)

Coons cubic B-spline

- piecewise C^2 continuous curve made of segments from Coons cubic curves with control points P_0, P_1, P_2, P_3 and P_1, P_2, P_3, P_4 etc.



Coons cubic B-spline

- given by a sequence of control points $P_0, P_1, \dots, P_n, n \geq 4$ in space, a uniform B-spline curve of third degree $R(t)$ compounded from $n-2$ Coons cubic curves is called Coons cubic B-spline

$$\mathbf{R}_0(t) = C_0(t)\mathbf{P}_0 + C_1(t)\mathbf{P}_1 + C_2(t)\mathbf{P}_2 + C_3(t)\mathbf{P}_3, t \in [0, 1],$$

$$\mathbf{R}_1(t) = C_0(t)\mathbf{P}_1 + C_1(t)\mathbf{P}_2 + C_2(t)\mathbf{P}_3 + C_3(t)\mathbf{P}_4, t \in [0, 1],$$

⋮

$$\mathbf{R}_{n-3}(t) = C_0(t)\mathbf{P}_{n-3} + C_1(t)\mathbf{P}_{n-2} + C_2(t)\mathbf{P}_{n-1} + C_3(t)\mathbf{P}_n, t \in [0, 1]$$

- closed or open
- **Example 2.13**

Coons cubic B-spline

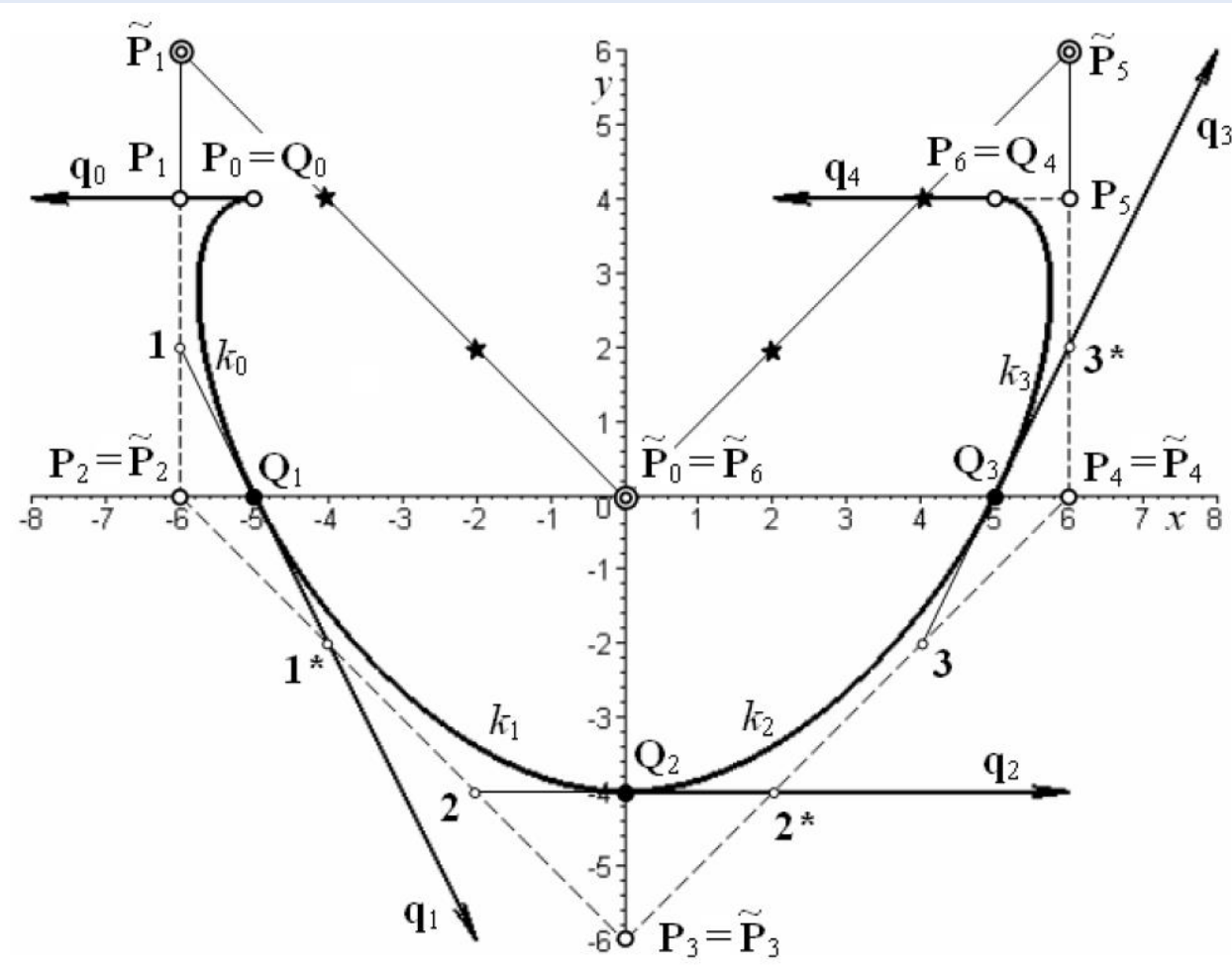
- **properties:**
 - control polygon is created by at least five control points
 - If the last three control points are identical with the first three control points, i.e. $P_n = P_2$, $P_{n-1} = P_1$, $P_{n-2} = P_0$, Coons cubic B-spline is closed, otherwise it is open
 - does not pass through any control point of its control polygon
 - is created by $n-2$ C^2 continuously joined Coons cubic curves, endpoints of these curves are called **knots** of Coons cubic B-spline
 - knots and tangent vectors at these knots can be constructed according to the properties

Coons cubic B-spline

- **properties:**
 - is a piecewise defined curve by partially overlapping control polygons (a change of position of one control point does not cause the change of whole Coons cubic B-spline, it influences the shape of those individual Coons cubic curves, of which vector equation contains the changing control point)
 - the domain of each individual Coons cubic curve is $t \in [0; 1]$
→ the curve is called a ***uniform curve*** or ***curve with a uniform parametrization***
- **Exercise 2.19**

Clamped curve

- = Uniform clamped B-spline curve of 3th degree
- segments are created by Bézier cubic curves/Coons cubic curves
- initial point is „ant centroid“ Q_0 of triangle $\tilde{P}_0\tilde{P}_1\tilde{P}_2$ constructed with respect to point \tilde{P}_1
- terminal point is „ant centroid“ Q_4 of triangle $\tilde{P}_4\tilde{P}_5\tilde{P}_6$ constructed with respect to point \tilde{P}_5
- P_1 is at the first third of tangent vector q_0 , on the leg $\tilde{P}_1\tilde{P}_2$ at one third from point \tilde{P}_1
- P_1 is on the leg $\tilde{P}_4\tilde{P}_5$ at one third from point \tilde{P}_4



Clamped curve

- transformation formulas between control points P_0, \dots, P_n of clamped curve and control points $\tilde{P}_0, \dots, \tilde{P}_n$ of open Coons cubic B-spline:

$$P_0 = Q_0 = \frac{1}{6}\tilde{P}_0 + \frac{2}{3}\tilde{P}_1 + \frac{1}{6}\tilde{P}_2,$$

$$P_1 = \frac{2}{3}\tilde{P}_1 + \frac{1}{3}\tilde{P}_2,$$

$$P_i = \tilde{P}_i, \quad i = 2, \dots, n-2,$$

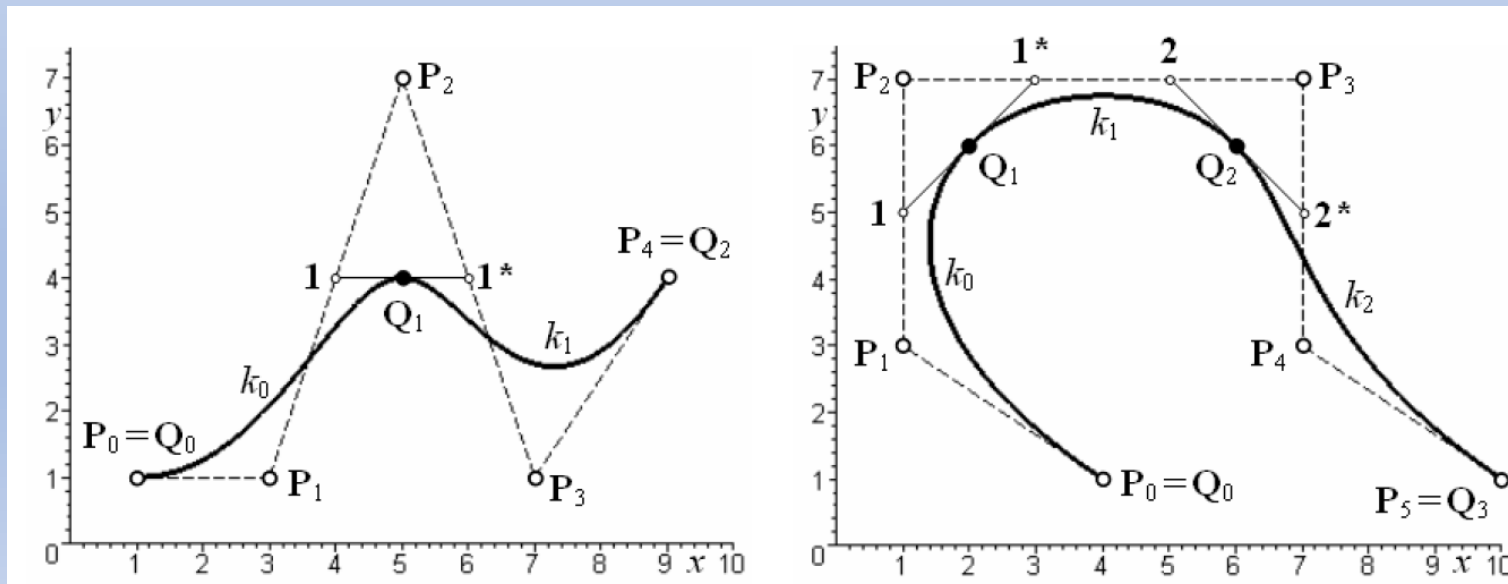
$$P_{n-1} = \frac{1}{3}\tilde{P}_{n-2} + \frac{2}{3}\tilde{P}_{n-1},$$

$$P_n = Q_{n-2} = \frac{1}{6}\tilde{P}_{n-2} + \frac{2}{3}\tilde{P}_{n-1} + \frac{1}{6}\tilde{P}_n$$

- first 2 and the last 2 curve segments are created by Bézier curves and all inner curve segments are created by Coons cubic curves (Coons cubic B-spline)

Clamped curve

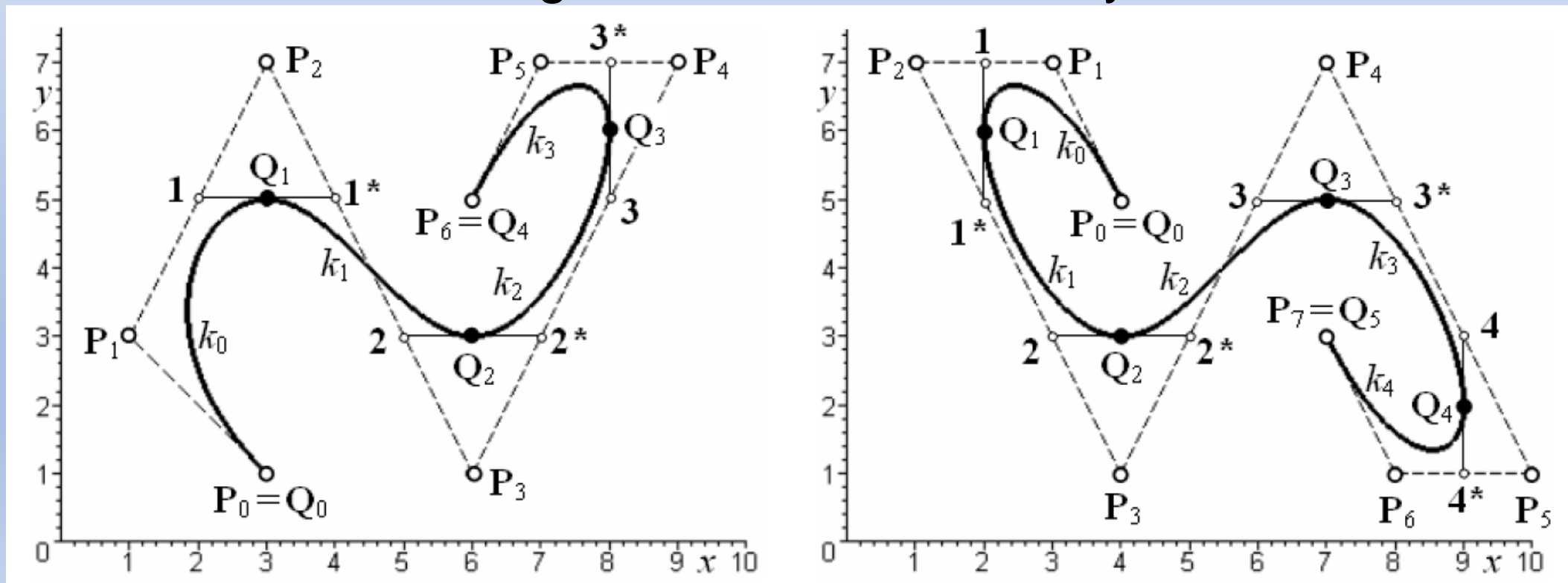
- **properties:**
 - from properties of Bézier cubic curve, Coons cubic curve and Coons cubic B-spline
 - for $n=3$: only one curve segment \rightarrow Bézier cubic curve
 - for $n=4$: two curve segments \rightarrow Bézier cubic curves
 - for $n=5$: three curve segments \rightarrow Bézier cubic curves



Clamped curve

- **properties:**

- for $n=6$: four curve segments \rightarrow Bézier cubic curves
- for $n=7$: five curve segments \rightarrow Bézier cubic curves, the middle curve segment is simultaneously Coons cubic curve



Clamped curve

- **properties:**

- for $n > 7$: $n-2$ curve segments \rightarrow first two and the last two curve segments are Bézier cubic curves, remaining $n-6$ internal curve segments are C^2 continuously joined Coons cubic curves (open Coons cubic B-spline)
- for $n \geq 3$ it is possible to create the clamped curve as a set of C^2 continuously joined Bézier cubic curves

Clamped curve

- **construction of knots of clamped curve for $n > 7$:**
 1. initial point Q_0 is equal to the first control point P_0
 2. terminal point Q_{n-2} is equal to the last control point P_n
 3. do **not** divide the first and the last leg of control polygon
 4. divide the second and the next-to-last leg of the control polygon in halves \rightarrow points 1 and $(n - 3)^*$
 5. divide the remaining internal legs in thirds \rightarrow points 1^* , 2 , 2^* , ...
 6. construct straight line segments 11^* , 22^* , ...
 7. knots Q_1 , Q_2 , ... lie at the centers of straight line segments 11^* , 22^* , ...

Clamped curve

- **Exercise 2.26**
- **Exercise 2.27** (*try yourself*)